

# Three Phase AC Induction Motors



#### Motors

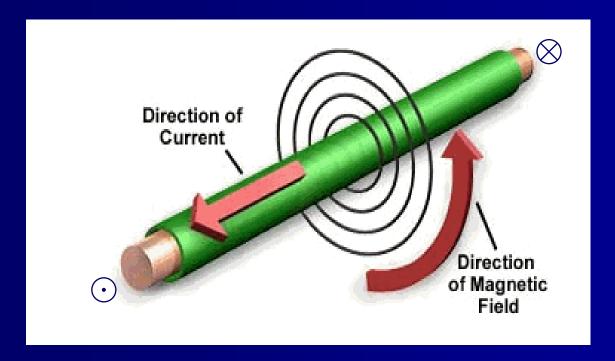
#### Motors convert Electrical energy into Mechanical energy





#### Magnetic Fields

When current flows in a conductor it produces a magnetic field about it - as shown below

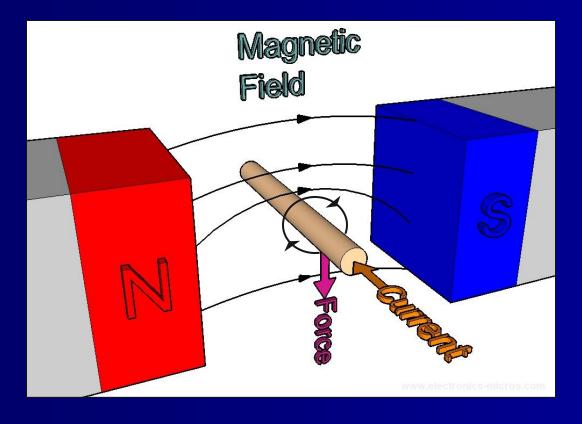


Using the corkscrew rule, we can see that the field is moving in an anticlockwise direction as we look at it.



#### **Motion**

When the current-carrying conductor is placed within an external magnetic field, the two fields interact, and a force is exerted on the conductor

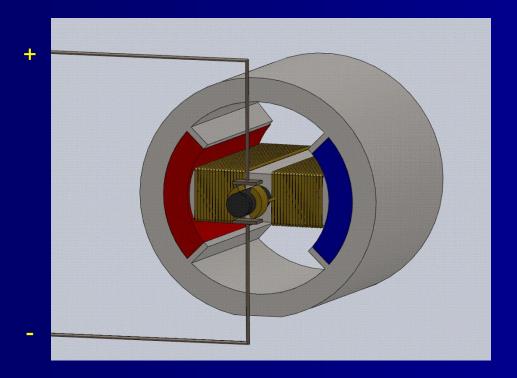


(Flemings Left Hand Rule)



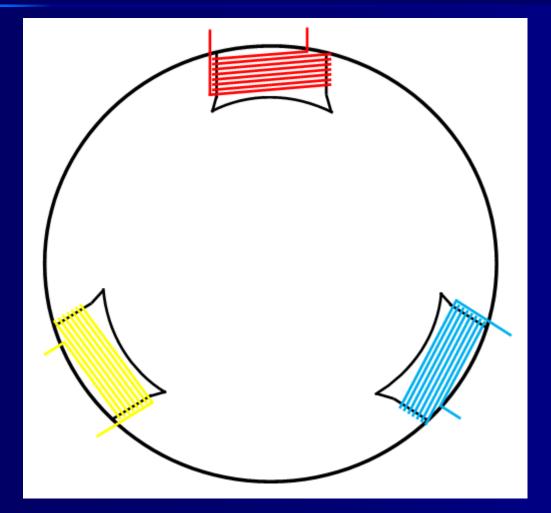
#### **Basic DC Motor**

If the current-carrying conductor is placed within an external magnetic field and coiled in a loop the conductor field can be increased in strength, the fields interact on both sides of the loop and a force is exerted on the conductors to make them rotate



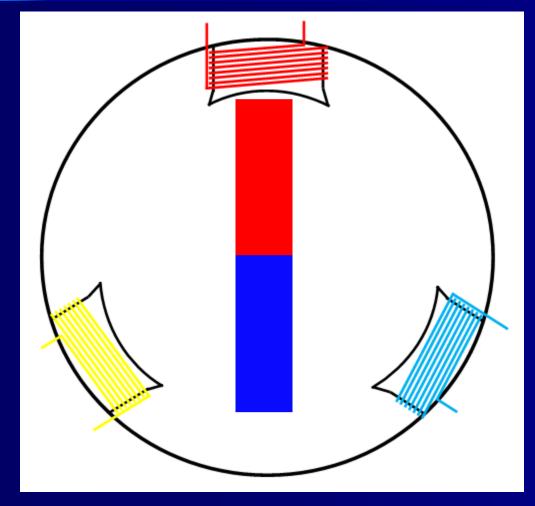


#### Three Phase AC Winding



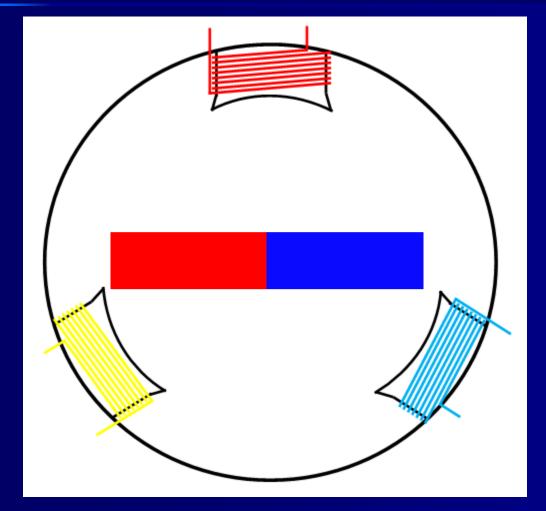
With three windings we can position them 120° apart to give us 3 pole faces

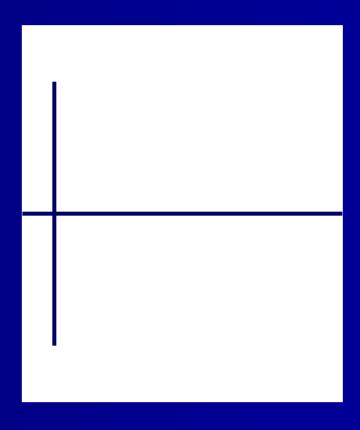




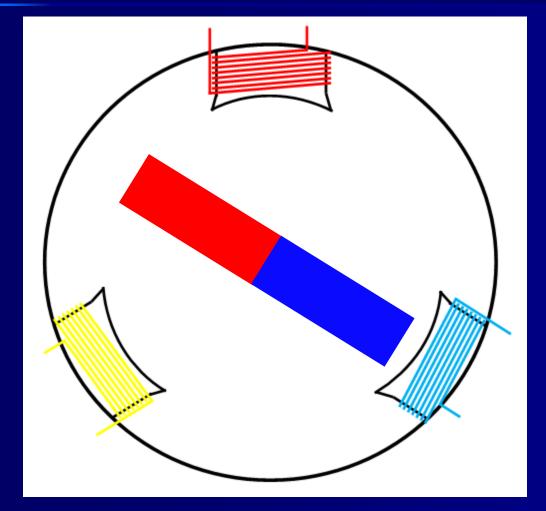
This is how a
Generator
would be
configured

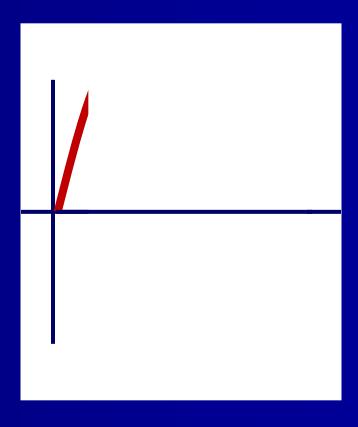




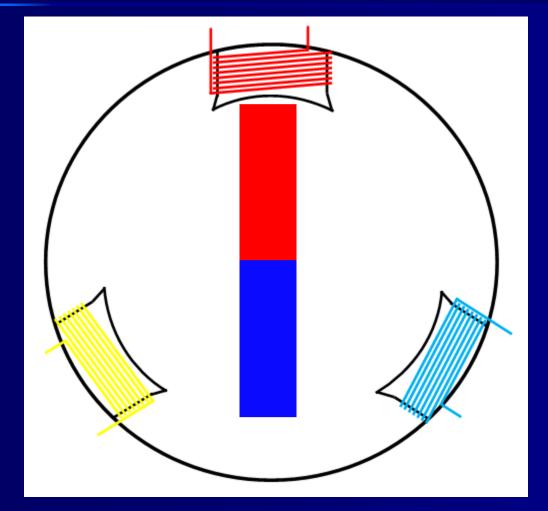


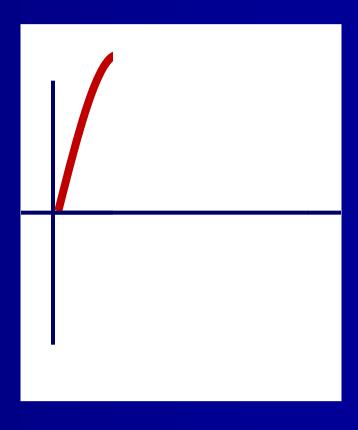




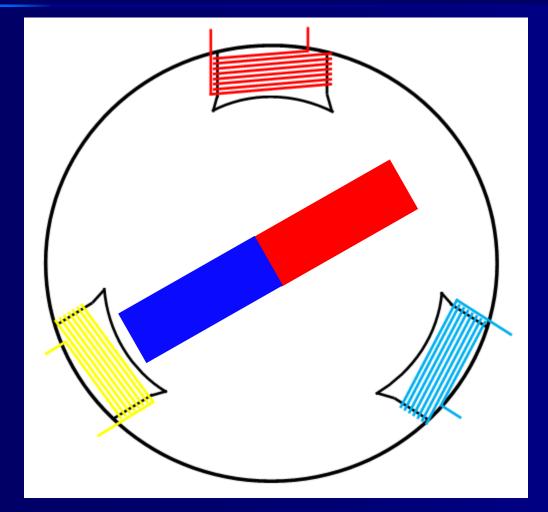


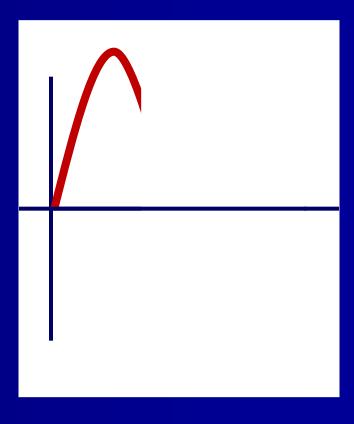




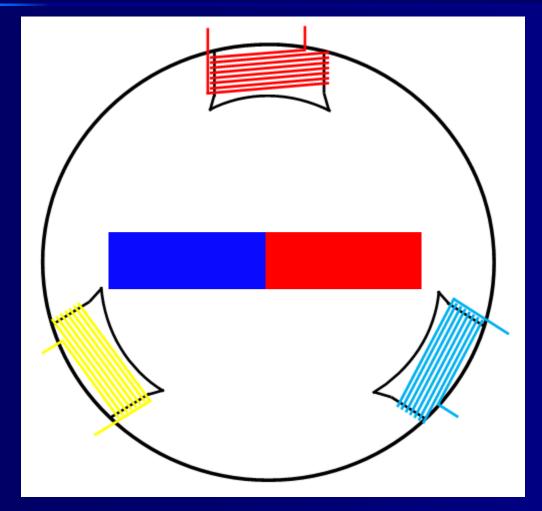


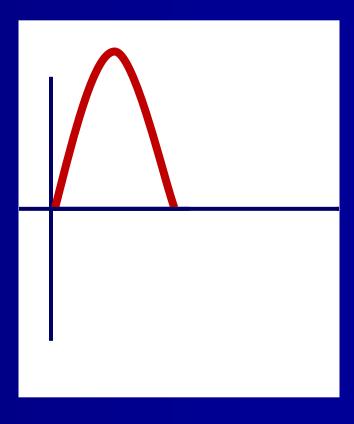




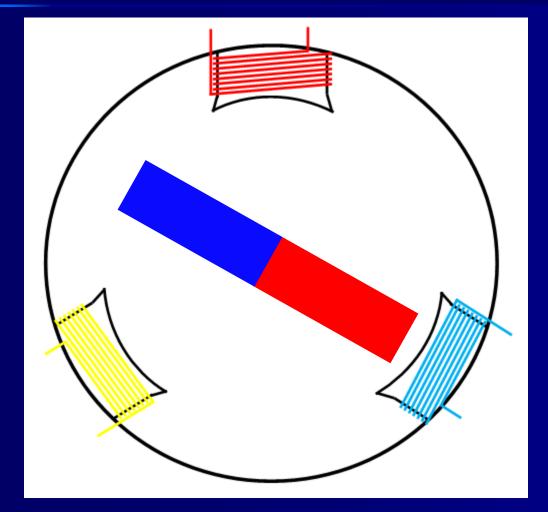


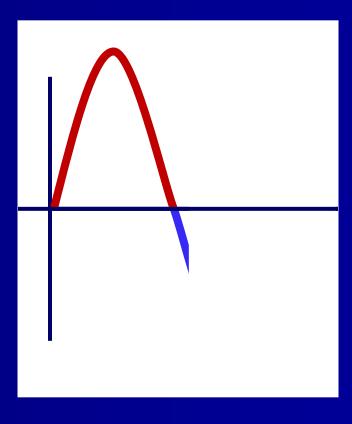




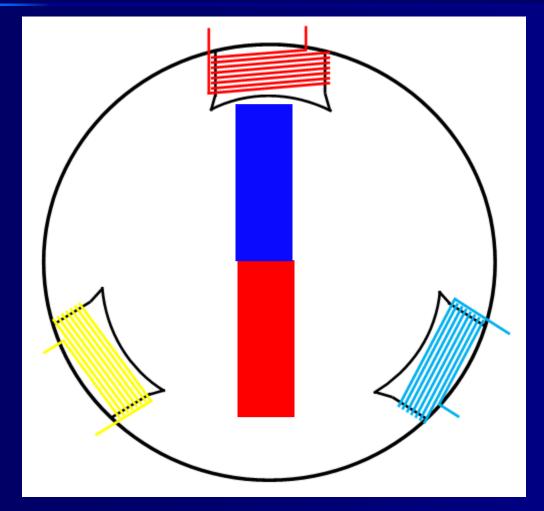


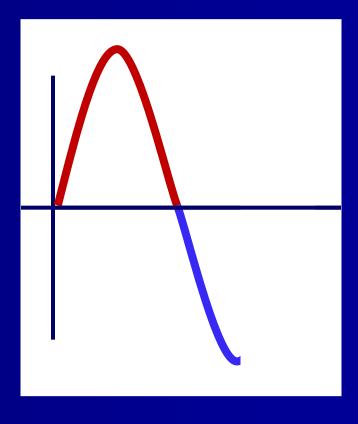




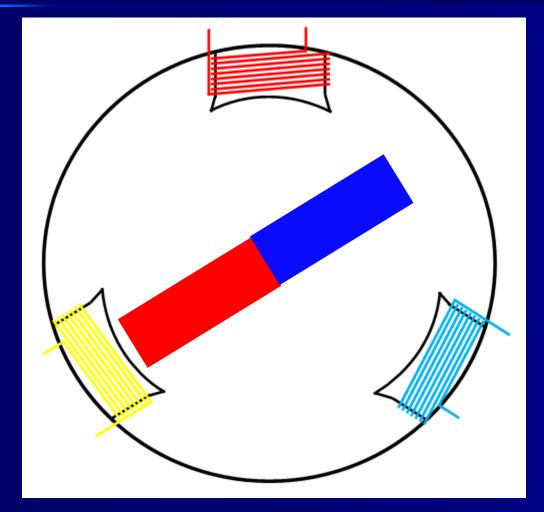


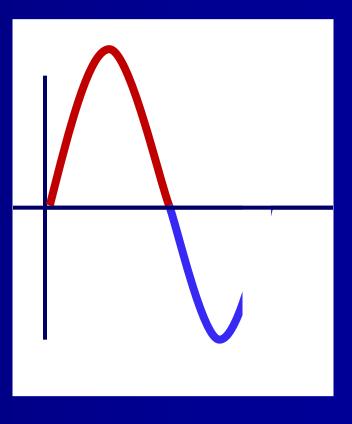




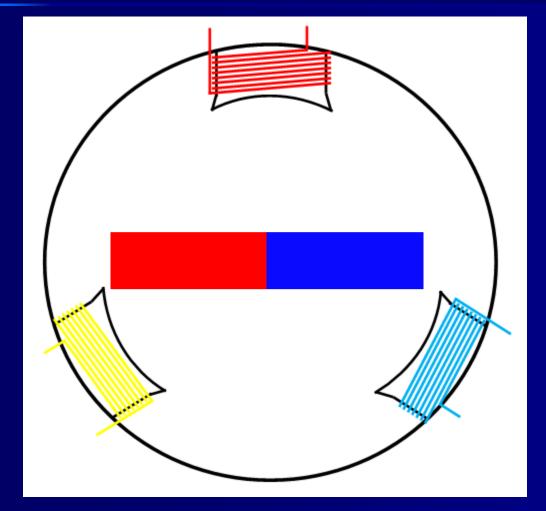


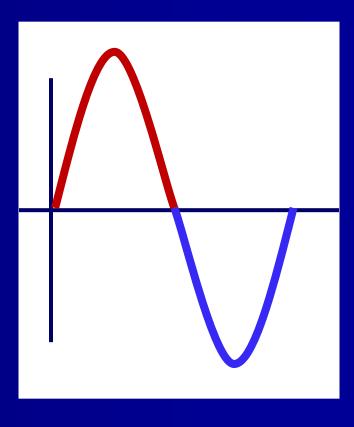






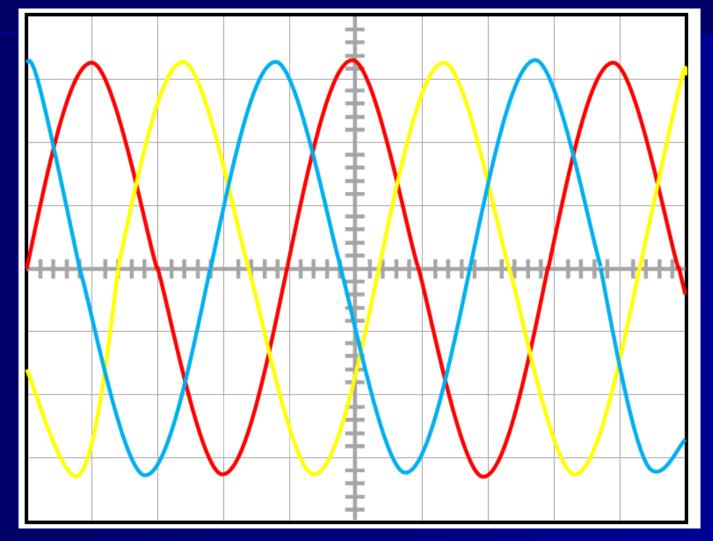






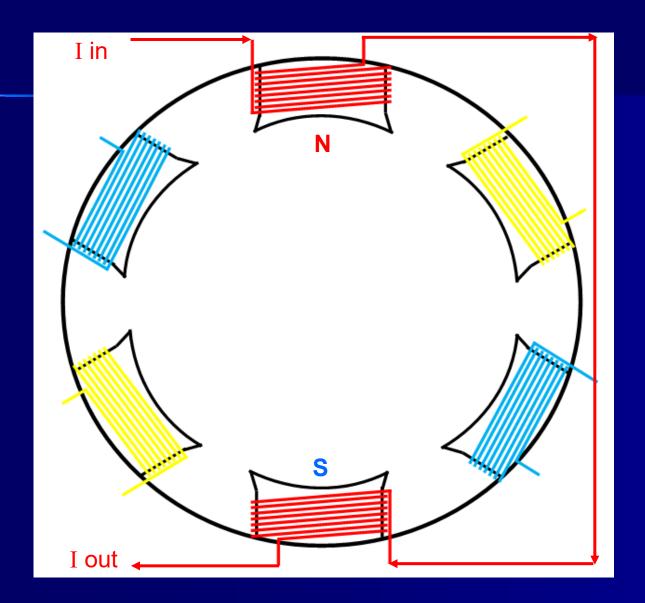


#### Three Phase Supply Rotation



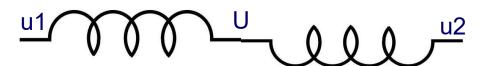
#### **Motor Stator Windings**

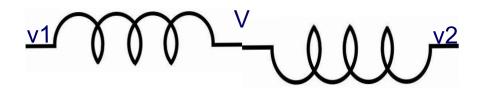


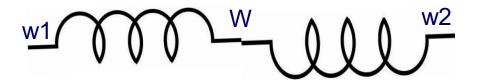


3Φ AC induction motors are wound to give us pole pairs, North & South for opposite pole faces. Here we have a 2-pole motor i.e., 2 poles per phase or 1 pole pair per phase

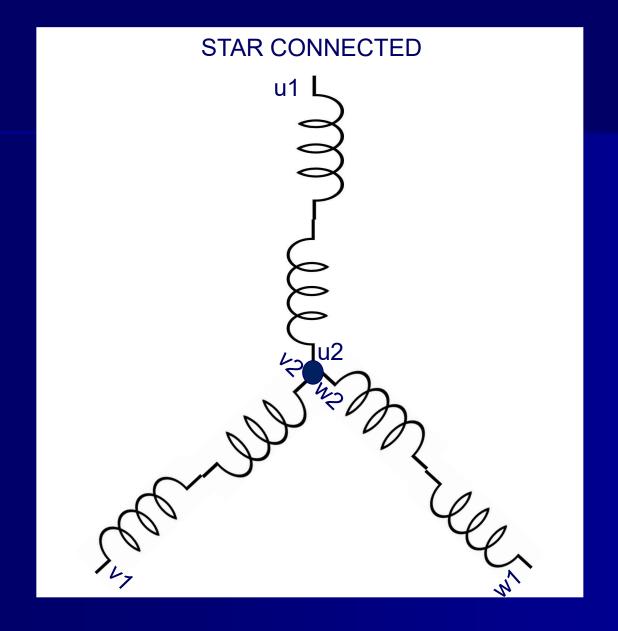




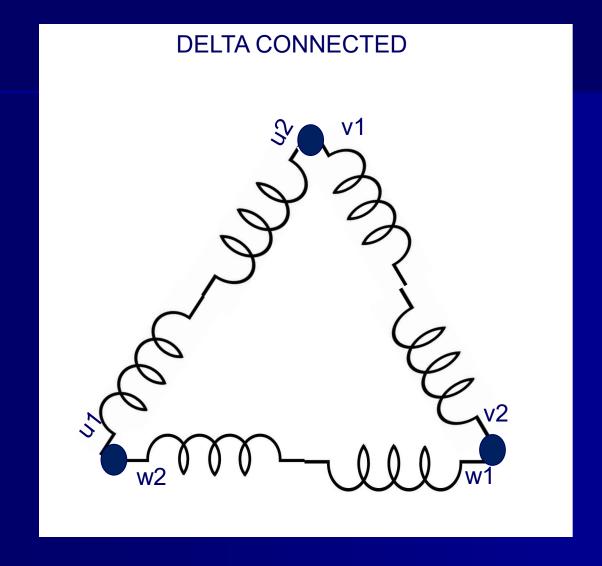






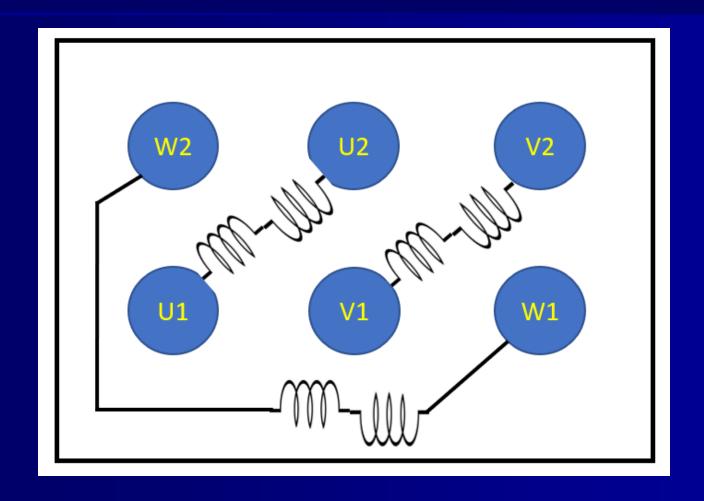




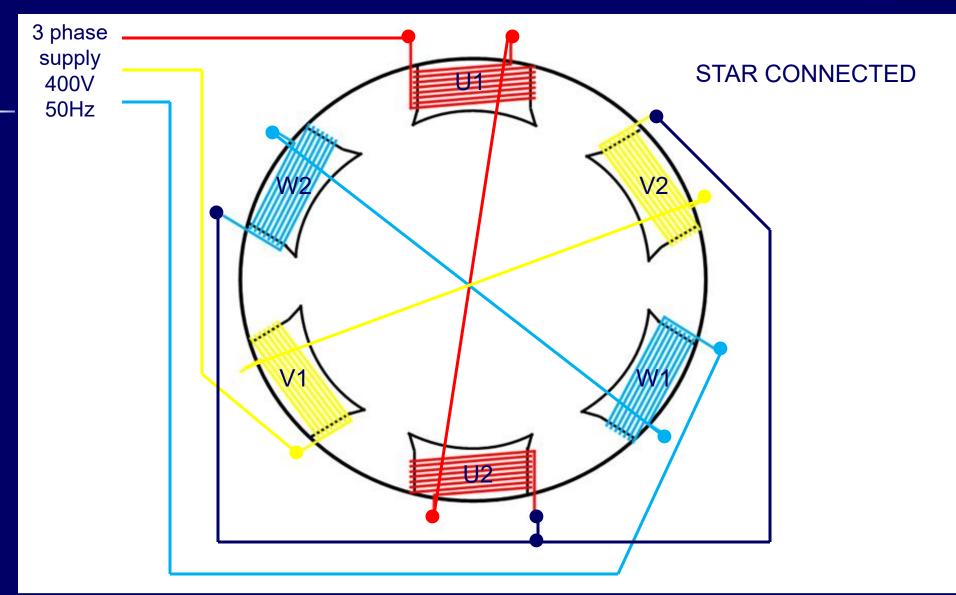




#### **Terminal Box Configuration**

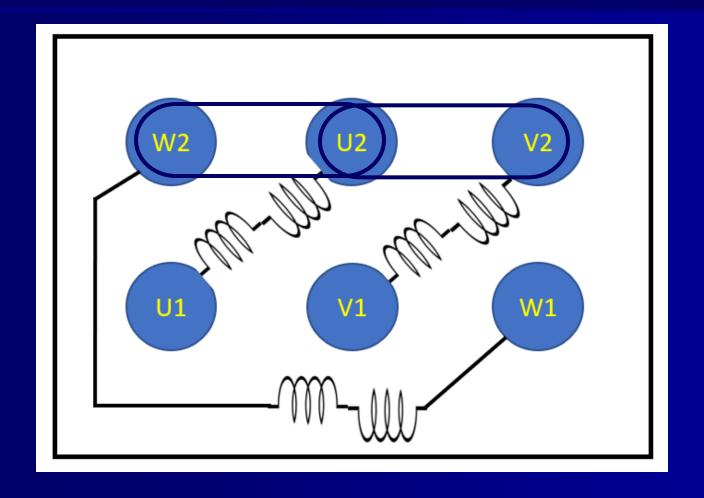






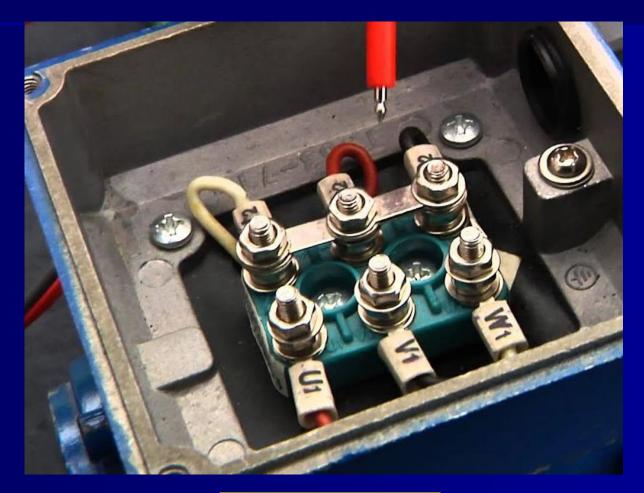


#### Terminal Box Star linked for Star



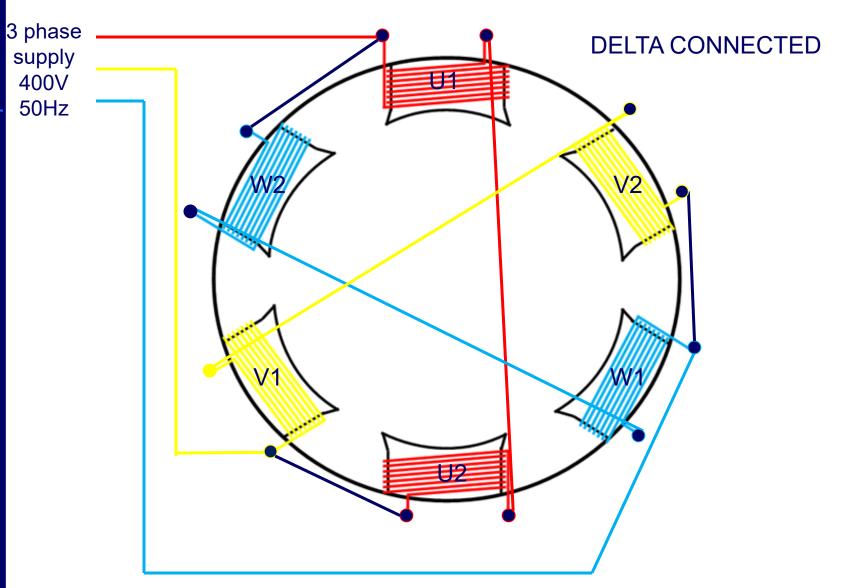


#### **Motor Links**



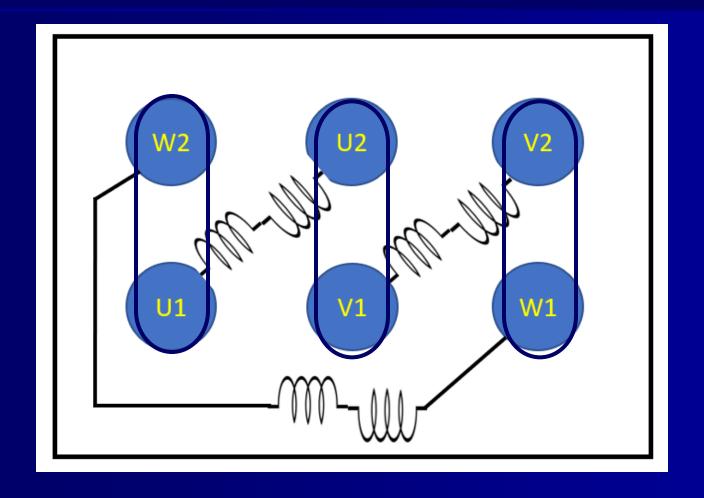
STAR CONNECTED





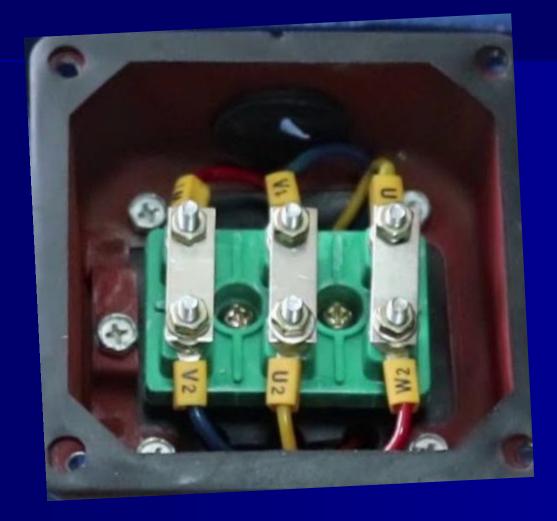


#### Terminal Box linked for Delta





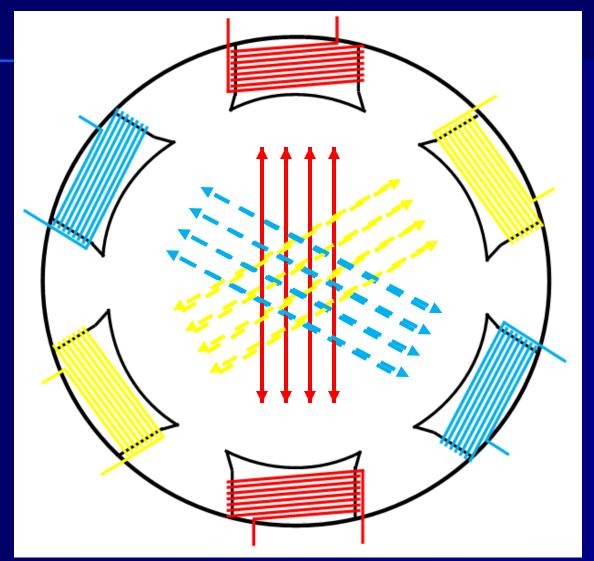
#### **Motor Links**



**DELTA CONNECTED** 



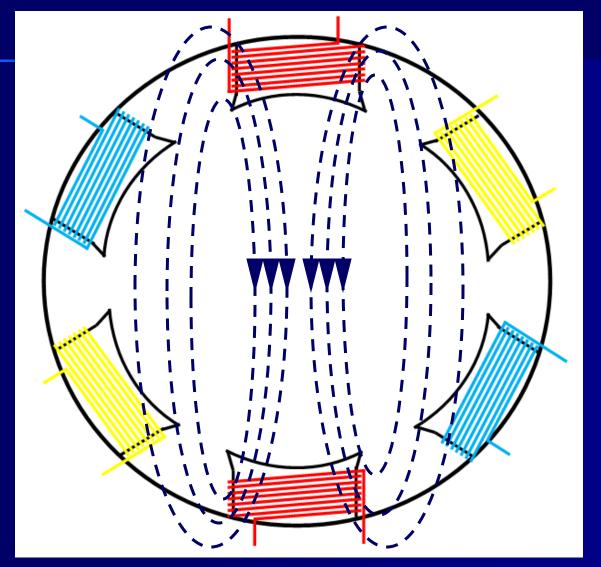
## **Three Phase Stator Windings**



With the three windings now configured for **STAR or DELTA** we can create pole faces that concentrate the magnetic fields as each phase peaks



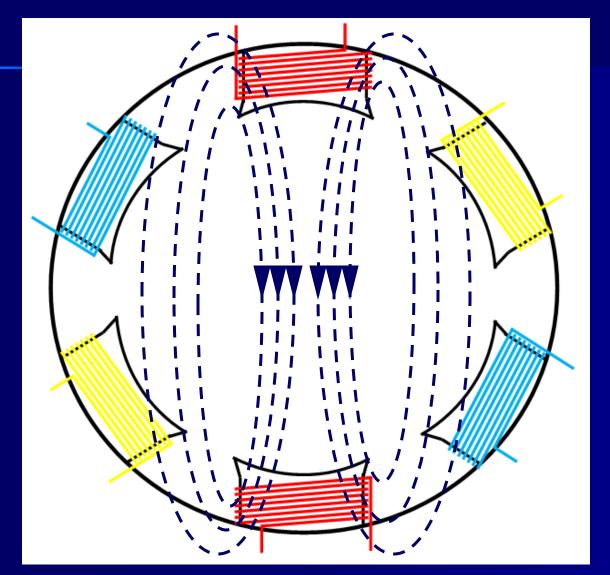
## **Three Phase Stator Windings**



The magnetic field will adopt the standard pattern created by a solenoid and due to phase rotation, it will appear to rotate



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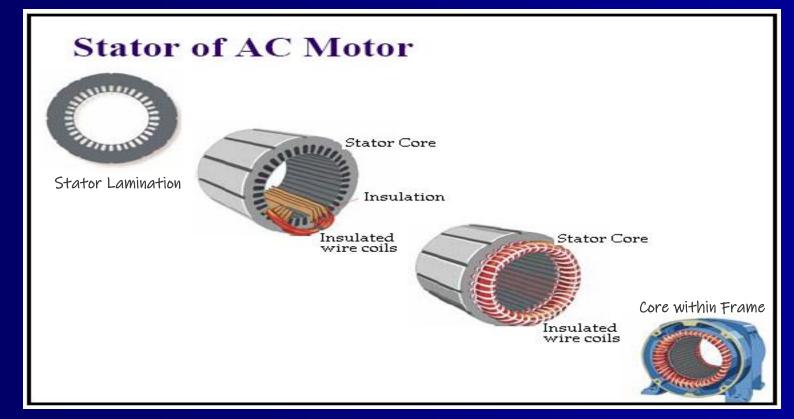
UK once every 20 milliseconds (50Hz)



#### **AC Cage Induction Motor**

This machine uses the same basic principles of motors but also utilises some of the technology of generators and is essentially consisting of two main parts.

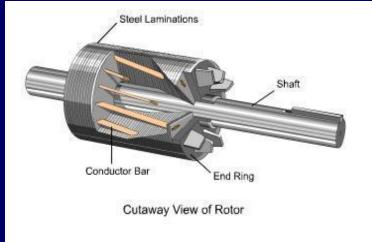
#### Stator

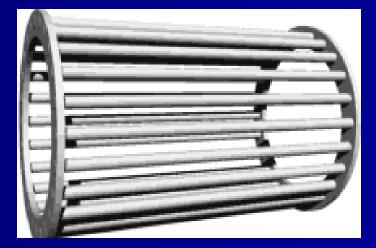




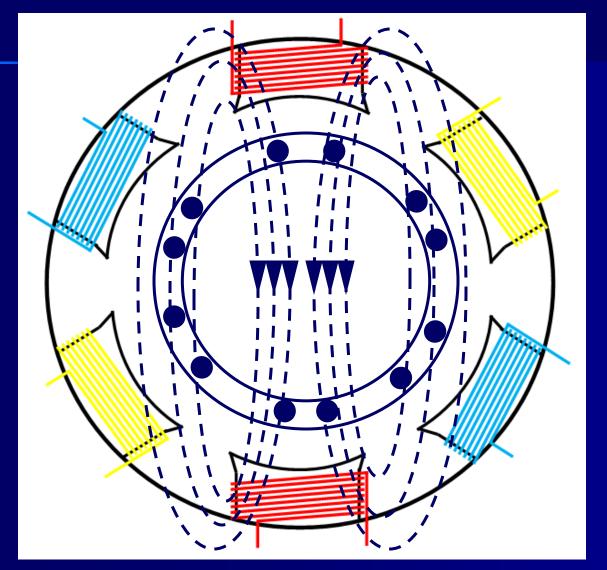
# AC Cage Induction Motor Cage Rotor





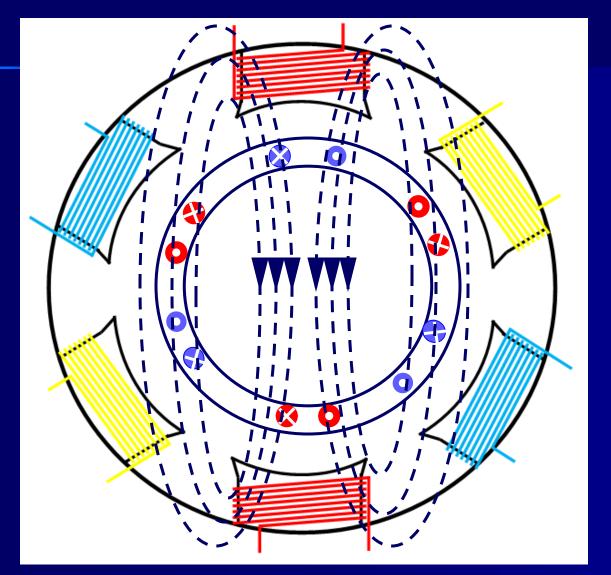






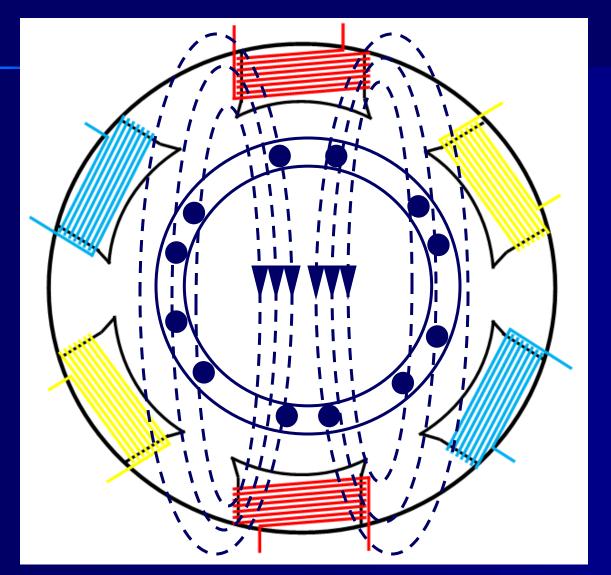
If we now place the cage rotor inside the rotating field of the stator that rotating field will induce a current into the bars of the cage as they are closed loops





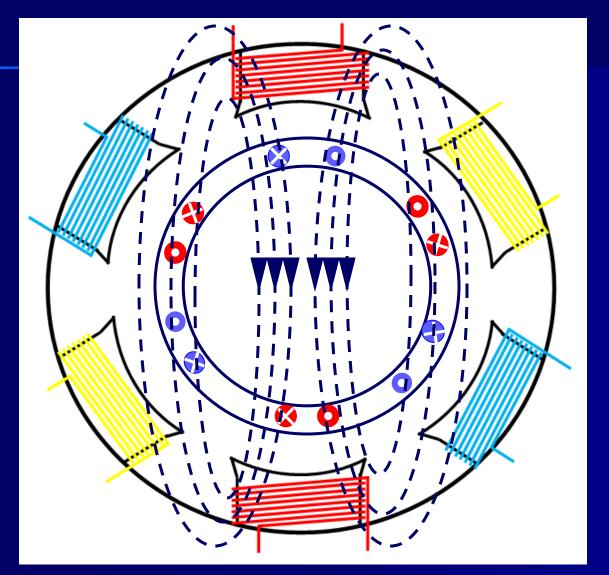
These individual loop currents will create their own fields which will try to lock on to the rotating stator field therefore the rotor will rotate in the direction of the rotating field



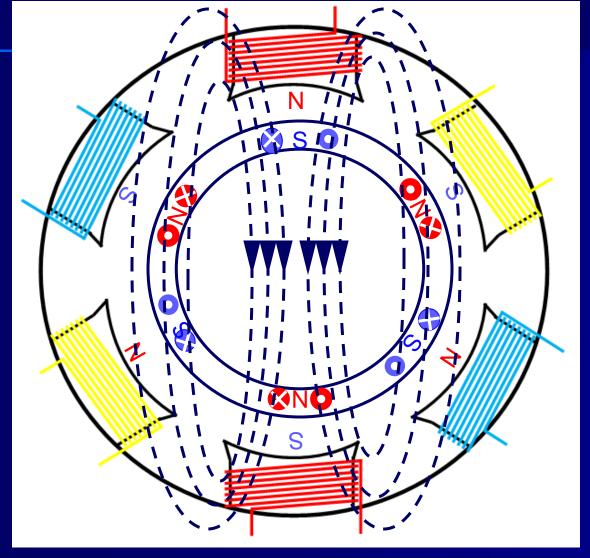


If the rotor catches up to the stator, they will become **synchronous**, and no current will be induced into the rotor bars, and it will slow down





The slowing down of the Rotor speed to less than the Stator field speed re induces current into the Rotor bars and the motor would speed up again



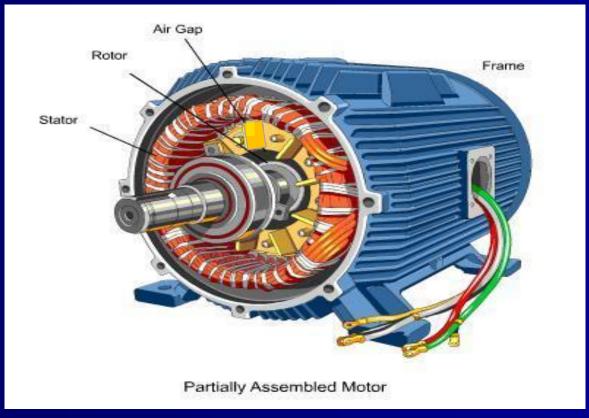


We clearly don't want the motor speeding up and slowing down so the Rotor is designed to run at slip speed (asynchronous) so, there is always interaction between the Rotor and the **Stator** 



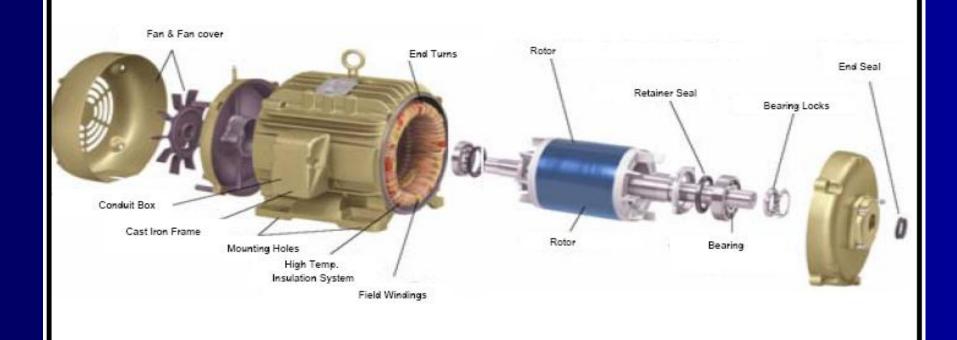


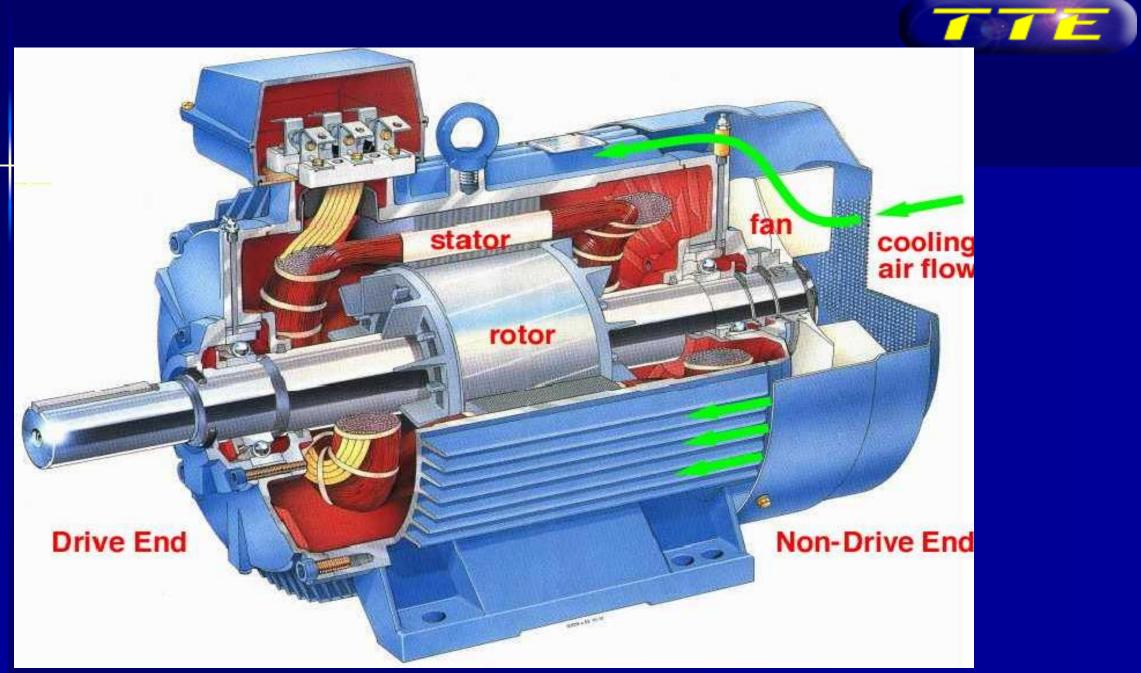
- It has three pairs of electromagnets, connected to each of the three phases of the power supply.
- It provides a lot higher power that a single-phase motor can deliver.





#### Parts of AC Motor









Each motor has a plate mounted on its frame, with electrical and mechanical information.

